ABSTRACT
The design of broadband antireflection (BBAR) coatings is based upon the indices of refraction of the materials to be used, the bandwidth required, the overall thickness of the coating, and the number of layers. Some useful tools have been found to guide the designer to optimal results such as: 1) recommended overall thickness; 2) observation of the low frequency (long wavelength) spectra beyond the AR band; 3) the reflectance versus coating thickness plot; 4) the shape of the passband trace, and 5) a definite number of layers required. It was also found that any more than the minimum number of layers increases the average reflectance. For small bandwidths, designs tend to require a number of layers equal to six times the parameter of overall thickness divided by the minimum thickness. Whereas 10 times that parameter are needed for large bandwidths. It has further been our experience that the optimization of a starting design, other than a design of only a few layers, tends to reach a conclusion at a local minimum which is not always the best that can be achieved in the general region of available variables. The best overall thickness parameter used has a tendency to be quantized. Design guides as to overall thickness, number of layers, and visual aids as to shape are provided.

INTRODUCTION
In the design of a BBAR coating, there are four factors which influence the results: 1) the refractive indices of the materials used; 2) the bandwidth over which the reflection is to be reduced; 3) the overall thickness of the coating, and 4) the number of layers in the design. The bandwidth is usually specified, leaving the materials, overall thickness, and number of layers as variables. The choice of materials is limited by the spectral range of interest and the environmental resistance desired—we have confined the materials used here to indices of 2.35 and 1.46. It will be emphasized here that there are definite lower limits on the overall thickness and number of layers for an optimal design, and that it is undesirable to exceed a certain upper range of overall thickness and the minimum number of layers for a given design problem.
LOCAL MINIMA AND QUANTIZATION

It has been our experience that the optimization of a starting design for a BBAR coating, other than one of only a few layers, tends to reach a conclusion at a local minimum which is not always the best that can be done in the general region of available variable parameters. The number of layers are specified by the designer to the optimization program, and the optimization is only on the thicknesses of the layers. The Rave and overall thickness of the coating results from these choices and the optimization process. We have written and used programs to constrain the results to a specific overall thickness, but this generally turns out to be unnecessary to achieve a desired result. Figure 4 shows the Rave results versus overall coating thickness at the end of optimization runs for a number of starting designs. Note that these seem to cluster at certain thickness intervals leading to the “true” minimum in a given thickness region. Figure 5 is a similar illustration for many optimized designs of a BBAR where B is 1.5 and the overall thickness varies over a range of more than 5 to 1. This illustrates the observation that optimized designs that are truly the minimum Rave for a given overall thickness region seem to be at quantized thickness intervals. Further evidence of this quantization is seen in Verly’s plot from our paper [3] on the Fourier viewpoint of AR coatings which is reproduced as Figure 6.

Figure 2: Same design as in Figure 1, but shown on expanded scale.

Figure 3: Reflectance versus coating thickness for the same design as in Figures 1 and 2 will be shown useful for design purposes below.

Figure 4: % Rave results after optimization versus thickness from a variety of starting designs.

Figure 5: Many optimized designs from different starting points as in Figure 4. B for this AR series versus thickness is 1.5.
The question then arises as to what constitutes one “quanta” of overall thickness (T). Several possible definitions were examined, and the simplest was chosen to be “one half wave of optical thickness at the lowest frequency (or longest wavelength) in the AR band.” This new definition would give the same result as the old [1] when B is equal to 4, but would differ for other B-values. It appears that the high frequency (or short wavelength) end of the AR band has little or no influence on the behavior associated with the overall thickness value. Verly, et al. [3] used the equivalent of our new definition in the work seen in Figure 6.

Note the similarity in the shapes of Figures 5 and 6. The minimum Rave (and “merit” function value) decreases with increasing thickness—rapidly at first and then with decreasing impact as the overall thickness increases. A further correlation and confirmation of this comes from a totally independent result by Thelen and Langfeld [4]. Figure 7 shows the results from their AR design contest with 44 competitive designs. The best of these are found to have the same decreasing Rave with thickness after some minimum thickness optimized design. The minimum overall thickness for the lower left design point in Figure 7 works out to be 1.125 times a half wavelength at the longest wavelength. In this figure, minima can also be seen near 2, 3, and 5 times this thickness, further supporting the quantization observation.

The bulk of the work reported in this paper was a new and fairly exhaustive set of designs in search of “true” minima in Rave over a broad range of B and overall thickness. Dispersion was not included in this work as it would not be expected to change the nature of the conclusions. The last layer of the lowest practical index available (1.38 in this region) as discussed extensively in the earlier works [1, 2] was also not used here for the same reasons. However, if we were designing a real system such as these for the visible and near IR region, we would in fact include a last layer of MgF2 in a design which was otherwise TiO2 and SiO2 in order to achieve even lower Rave per References 1 and 2. The reasons for not using just MgF2 and TiO2 for all of the layers is discussed in an earlier paper [5].

Figure 8 shows the results of “true” minima in Rave found in the range of B from 1.25 to 4 and T from 1 to 8. The same behavior as in Figures 6 and 7 is again observed. The quantization as a function of thickness seems to occur at about a half wavelength at the longest wavelength multiplied by
1.25. We will inject here that examination of Figure 6 by Verly et al. points to minima that seem to occur in intervals of a half wavelength at the longest wavelength multiplied by 1.33. Henceforth, a thickness cycle (C) will be referred to as a half wavelength at the longest wavelength multiplied 1.25. This was determined from a plot of C versus T for all of the cases from Figure 8 and a line of C equal to T/1.25, where the fit was adequate for the work at hand.

PREDICTION EQUATIONS

It can be seen in Figure 8 that Rave is a strong function of B and C up to C equal 3.0, but is a much weaker function of C (T) after that. Therefore, it was decided to treat the region where C < 3 separately from the region where C > 3. Design of Experiments (DOE) statistical techniques were used to find a best fit of the data and equation for Rave as a function of B and C. Because Rave improves so little with increasing C after C = 3, we do not recommend such designs (where C > 3 or T > 3.75 times the longest wavelength in the AR band) as practical solutions to real problems. However, we did make a fit-check between the two models for the two regions where they meet at C = 3.0. Figure 9 shows the predicted points from the first and second models as compared to the actual points for C = 3.0. The greatest departures here are less than 1/20th% in Rave, not a matter of any concern to us. The worst case errors in fit over both regions are of this same order and the Standard Errors are 0.029% and 0.039% respectively.

The equation which results to predict Rave in the region which we recommend, C < = 3.0 is:

\[
\text{Rave} = 0.36729 - 0.68978B + 0.49717BB - 0.06116BBB - 0.10757BC + 0.01875BCC
\] (1)

The equation for the region which we do not recommend, C > 3.0 is:

\[
\text{Rave} = -0.36944 + 0.22863B + 0.03522BB - 0.01010C
\] (2)

NUMBER OF LAYERS

In our earlier work [1, 2] it became apparent that there was a definite minimum for the number of layers required for an optimal AR of a given overall thickness. It was also found that any more than the minimum number of layers slightly increased Rave as seen in Figure 10. We conjecture that this is because each layer adds to the overall reflectance of the coating in a way which needs to be further dealt with, therefore there is an advantage to using the minimum number of layers required by the circumstances. It is our practice to attempt to remove the thinnest layer in any design and reoptimize the design in hopes of further decreasing the Rave. Often, the automatic optimization process will reduce one or more layers to a vanishingly small thickness without human intervention. In these cases, the layers can be removed from the design without any effect on the resulting Rave. An aid to understanding where layers can best be removed is a plot of reflectance versus thickness as shown in Figures 3 and 11. Each of these figures represent cases where the minimum number of layers has been reached, but if there were an unneeded layer, it might show up as a very thin layer in either of these plots. These plots are made for the lowest frequency in the AR band (or the longest wavelength). Figures 3 and 11 are both for cases where C = 3.0; this can be determined by number of cycles in reflectance seen from zero to maximum overall thickness in these figures. The same information is available as in Figure 2 by counting the number of reflectance maxima between zero and the lowest frequency in the AR band. Figure 2, however, gives no information as to the number of layers in the coating. Figure 3 is for a design where B = 3.5 whereas Figure 11 is for a case where B = 1.5.

Figure 9: Predicted points at C = 3.0 from both models and the actual data points from Figure 8 results.

Figure 10: Results from our earlier work [1, 2] where the number of layers was reduced until the least %Rave was found.
Figure 11: Reflectance versus thickness where $C = 3.0$ and $B = 1.5$. $B$ is small enough to require only 6 layers per cycle.

Figure 12: Number of layers in “true” optimal designs from Figure 8 as a function of $B$ and $C$.

It has been discovered that, for low $B$-values, these designs tend to require a number of layers equal to $6^\circ C$ to be optimal. Whereas $10^\circ C$ layers are needed for large $B$-values. Figure 11 illustrates the $6^\circ C$ case with 18 layers. In the central cycle of this plot, we observe a central high index layer which is flanked by a low/high layer pair on each side that leads to low index layers on each side of those between each maxima in reflection. It has been observed that the first and last cycles tend to be slightly different from any intervening cycles. The intervening cycles, which have been examined (up to $C = 7$) tend to be very similar and have either 6 or 10 layers as mentioned above. The cycle next to the substrate (first cycle) usually needs two extra layers at the substrate to provide an optimal design. The last cycle on the other end of the stack often performs better with two less layers. The result, with two more layers on the one end and two less layers on the other, is that the number for the overall thickness is still either 6 or 10 per cycle for small or large values of $B$ respectively. Figure 3 shows this for the $10^\circ C$ case and Figure 11 for the $6^\circ C$ case.

These reflectance versus thickness plots are closely related to effective index versus thickness plots which might result from a Fourier synthesis design as discussed in Reference 3. We interpret the need for 10 layers per cycle for high $B$-values to be due to a need to have smoother effective index transitions which more closely match the ideal index versus thickness profile and admittance plots as discussed in Chapter 1 of Reference 2. When the $B$-value is smaller, six layers per cycle are adequate because the need to match the ideal profile is less stringent.

It was found that there is a region between $B = 2$ and $B = 3.5$ where the optimal designs have layers per cycle which are intermediate between 6 and 10. These results are shown in Figure 12 where this region is referred to as the Transition Zone. The advice to the designer for cases such as these is to start with too many layers for a given $B$ and $C$, and reoptimize the design removing thinner layers as possible until a minimum Rave is achieved. It can be seen that the design of BBAR coatings is not strictly a matter of submitting a starting design to optimization software, because local minima are found more often that might have been expected. Evidence of this is seen in the Thelen-Langfeld contest results [4] shown in Figure 7. Only four of the designs submitted had minimal Rave for their overall thickness out of the 44 designs submitted. Knowing the number of layers which will lead to a minimal Rave for a given $B$ and $C$, and what that Rave should be, should be helpful to the BBAR designer.

MINIMA AND SHAPES

As can be seen in Figure 1, there are small minima in the AR band or ripples. These can be used to determine the overall thickness ($T$ via $C$) of a sample AR coating of unknown details. In the case of a V-coating such as a laser AR, there is one minimum in its narrow band. Three and four layer AR coatings usually have two minima in the band. With the much broader band AR coatings, we have found that the number of minima is predicted by: $B(C+1)-1$. This even fits the V-coat and 3 and 4-layer AR cases. Figure 13 shows the results of the optimal cases reported here, and this could be used as a look-up chart to determine $C$ when $B$ and the number of the minima in the band are measured on a spectrophotometer.
There is a somewhat similar behavior in the shape of the passband trace as seen in Figure 1. Most optimal designs reach a regular rippled trace like that of Figure 1. The slope of that trace can often be changed and leveled by adjustment of the optimization targets, although the Rave tends to remain the same. When less than the minimum number of layers for a given B and C are used, this mono-frequency ripple can become highly distorted by the appearance of additional frequency components. This can also be an indication of a potential for improvement in a design.

**CONCLUSIONS**

Our earlier work on the general nature and behavior of broadband AR coatings has been expanded here. Equations with additional accuracy to predict the average reflectance in the AR band have been developed with the aid of modern statistical analysis tools (DOE). The overall thickness parameter used in the equations has also been better defined and understood, and the tendency of overall thicknesses to have quantization has been demonstrated. The use of overall thicknesses greater than three cycles is proscribed because of their almost negligible benefit. Design guides as to overall thickness, number of layers, and visual aids as to shape have been provided.

**REFERENCES**


